

Sec 2.1

Linear Transformations and Matrices

classmate

Date _____

Page _____

2.1 Linear Transformations, null spaces, and ranges.

Def. Let V, W be vector spaces (over F).
 $T: V \rightarrow W$ is a linear transformation from V to W
if $\forall x, y \in V$ and $c \in F$, we have

(a) $T(cx + y) = cT(x) + T(y)$ and

(b) $T(cx) = cT(x)$

Thm. (If F is field of rationals then (a) \Rightarrow (b))

1. If T is linear, then $T(0) = 0$ ($c=0$ in (b))

2. T is linear iff $T(cx + y) = cT(x) + T(y)$
 $\forall x, y \in V$ and $c \in F$.

3. If T is linear, then $T(x - y) = T(x) - T(y)$.

(4) T is linear iff, $x_1, x_2, \dots, x_n \in V$ and $a_1, a_2, \dots, a_n \in F$
we have $T(\sum a_i x_i) = \sum a_i T(x_i)$

we will use (2) for proving that T is linear.

Ex $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(a_1, a_2) = (2a_1 + a_2, a_1)$
 $x, y \in \mathbb{R}^2$ & $x = (b_1, b_2)$ & $y = (d_1, d_2)$
 $cx + y = (cb_1 + d_1, cb_2 + d_2)$

we have:

$$T(cx+dy) = (2(cx+dy) + cb_2 + d_2, cb_1 + d_1)$$

$$\begin{aligned} \text{Also } cT(x) + T(y) &= c(2b_1 + b_2, b_1) + (2d_1 + d_2, d_1) \\ &= (2cb_1 + cb_2 + 2d_1 + d_2, cb_1 + d_1) \\ &= (2(cb_1 + d_1) + cb_2 + d_2, cb_1 + d_1) \end{aligned}$$

$\Rightarrow T$ is linear.

ex. For any angle θ , define $T_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$T_\theta(a_1, a_2)$ is the vector obtained by rotating (a_1, a_2) counterclockwise by θ if $(a_1, a_2) \neq (0,0)$ and $T_\theta(0,0) = (0,0)$. Then $T_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation that is called the rotation by θ .

Formula for T_θ -

$$\text{let } (a_1, a_2) \in \mathbb{R}^2$$

let α be the angle that (a_1, a_2) makes with the positive x-axis

$$\text{let } r = \sqrt{a_1^2 + a_2^2}$$

$$\Rightarrow a_1 = r \cos \alpha \quad \& \quad a_2 = r \sin \alpha$$

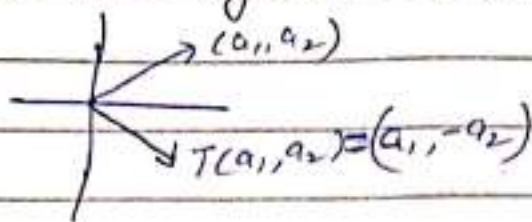
$T_\theta(a_1, a_2)$ has length r and makes an angle $\alpha + \theta$ with the x-axis.

$$\begin{aligned} \text{Also } T_\theta(a_1, a_2) &= (r \cos(\alpha + \theta), r \sin(\alpha + \theta)) \\ &= (r(\cos \alpha \cos \theta - \sin \alpha \sin \theta), r(\cos \alpha \sin \theta + \sin \alpha \cos \theta)) \\ &= (a_1 \cos \theta - a_2 \sin \theta, a_1 \sin \theta + a_2 \cos \theta) \end{aligned}$$

This formula is also valid for $(a_1, a_2) = (0,0)$.
Hence T_θ is linear transformation.

Ex $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(a, a_2) = (a_1, -a_2)$. T is

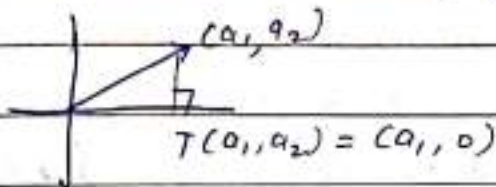
called the reflection about the x -axis



$$\begin{aligned} T(cx+cy) &= T(ca_1+b_1, ca_2+cb_2) \\ &= (ca_1+b_1, -ca_2-cb_2) \\ &= c(a_1, -a_2) + (b_1, -b_2) \end{aligned}$$

Ex Define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(a_1, a_2) = (a_1, 0)$.

T is called the projection on the x -axis.



Ex Define $T: M_{m \times n}(F) \rightarrow M_{n \times m}(F)$ by $T(A) = A^t$

$$T(cA+B) = (cA+B)^t = cA^t + B^t = cT(A) + T(B) \quad (c \in F)$$

Ex $T: P_n(\mathbb{R}) \rightarrow P_n(\mathbb{R})$ by $T(f(x)) = f'(x)$

$$\begin{aligned} T(a \cdot g(x) + h(x)) &= (a \cdot g(x) + h(x))' = a g'(x) + h'(x) \\ &= a T(g(x)) + T(h(x)) \end{aligned}$$

Ex Let $V = C[a, b]$ ^{v.s. of} continuous ~~real~~ real valued fun. on \mathbb{R}

Let $a, b \in \mathbb{R}$ & $a < b$. Define $T: V \rightarrow \mathbb{R}$ by

$$T(f) = \int_a^b f(x) dx$$

$$T(cf+g) = \int_a^b (cf+g) = c \int_a^b f + \int_a^b g$$

Identity Transformation

$$I_V: V \rightarrow V \text{ by } I_V(x) = x \quad \forall x \in V$$

& Zero Transformation

$$I_0: V \rightarrow W \text{ by } I_0(x) = 0, \quad \forall x \in V.$$

Def: Let V and W be vector spaces, and let $T: V \rightarrow W$ be linear. Define the null space (or kernel) $N(T)$ of T to be the set of all vectors x in V such that $T(x) = 0$; that is $N(T) = \{x \in V; T(x) = 0\}$. Range (or image) $R(T)$ of T is the subset of W consisting of all images (under T) of vectors in V . i.e. $R(T) = \{T(x); x \in V\}$

Ex Let V & W be vector spaces and let $I: V \rightarrow V$ & $T_0: V \rightarrow W$ be identity & zero transf. Then $N(I) = \{0\}$, $R(I) = V$, $N(T_0) = V$, $R(T_0) = \{0\}$.

Ex $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by $T(a_1, a_2, a_3) = (a_1, -a_2, 2a_3)$ is a L.T.
 $N(T) = \{(a, a, 0); a \in \mathbb{R}\}$ & $R(T) = \mathbb{R}^2$

Thm Let v & w be v.s. & $T: V \rightarrow W$ be a linear transformation. Then $N(T)$ & $R(T)$ are subspaces of V & W , respectively.

pr: 0_v & 0_w denote the zero vectors of V & W , respectively.

Since $T(0_v) = 0_w$

$$\Rightarrow 0_v \in N(T) \Rightarrow N(T) \neq \emptyset$$

Let $x, y \in N(T)$ & $c \in F$.

$$\text{Then } T(x+y) = T(x) + T(y) = 0_w + 0_w = 0_w.$$

$$\text{So } x+y \in N(T)$$

$$\& T(cx) = cT(x) = c \cdot 0_w = 0_w$$

$$\Rightarrow cx \in N(T)$$

$\Rightarrow N(T)$ is a subspace of V .

Because $T(0_v) = 0_w$,

$$\Rightarrow 0_w \in R(T) \Rightarrow R(T) \neq \emptyset$$

Let $x, y \in R(T)$ & $c \in F$

$$\Rightarrow \exists v \& w \text{ in } V \text{ s.t.}$$

$$T(v) = x \& T(w) = y.$$

$$\Rightarrow T(v+w) = T(v) + T(w) = x+y.$$

$$\Rightarrow x+y \in R(T)$$

$$\& T(cv) = cT(v) = cx$$

$$\Rightarrow cx \in R(T)$$

$\Rightarrow R(T)$ is a subspace of W .

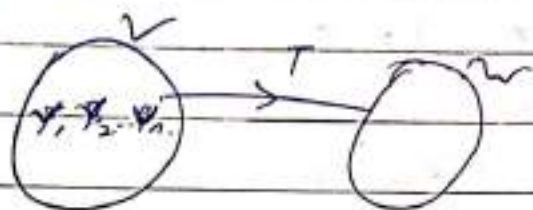
Now we will next then provide us method

for finding spanning set for the range of a L.T. from which we can find a basis for range by finding L.I. set from this spanning set.

Thm: Let V & W be vector spaces, and let $T: V \rightarrow W$ be linear. If $\beta = \{v_1, v_2, \dots, v_n\}$ is a basis for V , then

$$R(T) = \text{span}(T(\beta)) = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\}$$

pr:



clearly $T(v_i) \in R(T) \quad \forall i$

$$\Rightarrow \{T(v_1), T(v_2), \dots, T(v_n)\} \subseteq R(T)$$

& $R(T)$ is a subspace

$$\Rightarrow \text{span}\{T(v_1), \dots, T(v_n)\} \subseteq R(T)$$

$$\text{but } \{T(v_1), \dots, T(v_n)\} = T(\beta)$$

if R is a subspace
& $S \subseteq R$
then $\text{span} S \subseteq R$

$$\Rightarrow \text{span } T(\beta) \subseteq R(T)$$

let $w \in R(T)$

$$\Rightarrow w = T(v) \text{ for some } v \in V$$

some β is basis for V

$$\Rightarrow v = \sum_{i=1}^n a_i v_i \text{ for some } a_1, a_2, \dots, a_n \in F$$

Since T is linear

$$\begin{aligned} T(v) &= T\left(\sum a_i v_i\right) \\ &= \sum a_i T(v_i) \end{aligned}$$

$$w = \sum a_i T(v_i) \in \text{span } T(\beta)$$

$$\Rightarrow R(T) \subseteq \text{span } T(\beta)$$

$$\Rightarrow R(T) = \text{span}(T(\beta)) = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\}$$

Above this is also true if β is infinite.

Ex Define $T: P_2(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ by

$$T(f(x)) = \begin{pmatrix} f(1) - f(2) & 0 \\ 0 & f(0) \end{pmatrix}$$

since $\beta = \{1, x, x^2\}$ is a basis for $P_2(\mathbb{R})$, we have

$$R(T) = \text{span}(T(\beta))$$

$$= \text{span}(\{T(1), T(x), T(x^2)\})$$

$$= \text{span}\left(\left\{ \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} -3 & 0 \\ 0 & 0 \end{pmatrix} \right\}\right)$$

$$= \text{span}\left(\left\{ \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \right\}\right) \begin{matrix} \text{L.D.} \\ \text{S.L.T.} \end{matrix}$$

Thus basis for $R(T)$ is $\left\{ \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \right\}$

So $\dim R(T) = 2$

We measure the "size" of a subspace by its dimension.

Def: Let V & W be vector spaces, and let $T: V \rightarrow W$ be linear. If $N(T)$ & $R(T)$ are finite dimensional, then we define the nullity of T , denoted by $\text{nullity}(T)$, & the rank of T , denoted by $\text{rank}(T)$, to be the dimension of $N(T)$ & $R(T)$, respectively.

Intuitively we can see that ~~larger the nullity, smaller the rank~~, & vice versa.

Thm. Dimension Theorem.

Let V & W be vector spaces, and let $T: V \rightarrow W$ be linear. If V is finite dimensional, then

$$\text{nullity}(T) + \text{rank}(T) = \dim(V)$$

Pr: Let $\dim V = n$, $\dim(N(T)) = k$ and

$\{v_1, v_2, \dots, v_k\}$ is basis for $N(T)$

$\Rightarrow \{v_1, v_2, \dots, v_k\}$ is L.I. subset in V

Extend this L.I. set to basis of V .

Let $\beta = \{v_1, v_2, \dots, v_n\}$ is basis for V .

claim $S = \{T(v_{k+1}), T(v_{k+2}), \dots, T(v_n)\}$ is a basis for $R(T)$

first we will prove that S generate $R(T)$

Now $T(v_i) = 0 \quad \forall 1 \leq i \leq k$

because $\{v_i\}$ for $1 \leq i \leq k$ is basis for $N(T)$.

$$\Rightarrow v_i \in N(T) \Rightarrow T(v_i) = 0$$

previous
by above Thm.

$$\begin{aligned} R(T) &= \text{span} \{ T(v_1), T(v_2), \dots, T(v_n) \} \\ &= \text{span} \{ T(v_{k+1}), \dots, T(v_n) \} \\ &= \text{span}(S). \end{aligned}$$

Now we prove that S is L.I.

$$\text{Let } \sum_{i=k+1}^n b_i T(v_i) = 0 \quad \text{for } b_{k+1}, b_{k+2}, \dots, b_n \in \mathbb{F}$$

Now T is linear

$$\Rightarrow T\left(\sum_{i=k+1}^n b_i v_i\right) = 0 \quad \left\{ T\left(\sum b_i v_i\right) = \sum b_i T(v_i) \right\}$$

$$\Rightarrow \sum_{i=k+1}^n b_i v_i \in N(T).$$

β basis for $N(T)$ is $\{v_1, v_2, \dots, v_k\}$

$$\Rightarrow \exists c_1, c_2, \dots, c_k \in \mathbb{F} \text{ s.t.}$$

$$\sum_{i=k+1}^n b_i v_i = \sum_{i=1}^k c_i v_i$$

$$\Rightarrow \sum_{i=1}^k (-c_i) v_i + \sum_{i=k+1}^n b_i v_i = 0$$

Since $\beta = \{v_1, v_2, \dots, v_k\}$ is basis for N

$$\Rightarrow b_i = 0 \quad \forall i \quad (\text{also } c_i = 0)$$

$$\Rightarrow S \text{ is L.I.}$$

Also $T(v_{k+1}), T(v_{k+2}), \dots, T(v_n)$ are distinct.

$$\Rightarrow \text{rank}(T) = n - k$$

as they are
L.I.

$$\begin{aligned} \times \quad (\exists j \quad T(v_i) = T(v_j) \quad (i \neq j), \quad k+1 \leq i, j \leq n) \\ \Rightarrow T(v_i - v_j) = 0 \Rightarrow v_i - v_j \in N(T). \end{aligned}$$

$$v_i - v_j = \sum_{i=1}^k a_i v_i$$

$$\Rightarrow a_1 v_1 + a_2 v_2 - \dots + a_k v_k - v_i + v_j + 0 \left(\begin{array}{l} \text{sum} \\ \text{rest } v_i \end{array} \right)$$

which contradicts that $\{v_1, \dots, v_n\}$ is L.I.

Ex

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$T(a_1, a_2, a_3) = (a_1, -a_2, 2a_3)$$

$$N(T) = \{(a, a, 0) \mid a \in \mathbb{R}\}$$

$$\& \text{rank}(T) = 2$$

$$\Rightarrow \text{nullity } T + \text{rank } T = 3$$

$$\Rightarrow \text{nullity } T + 2 = 3$$

$$\Rightarrow \text{nullity } T = 1$$

Thm: Let V & W be V -spaces, and let $T: V \rightarrow W$ be linear. Then T is I.T. iff $N(T) = \{0\}$.

(i.e. nullity $T = 0$)
(or nullity $T = 0 \Rightarrow$)

Pr: Let T is I.T. & $x \in N(T)$. Then

$$T(x) = 0 = T(0)$$

Since T is I.T. $\Rightarrow x = 0$.

$$\Rightarrow N(T) = \{0\}$$

Con let $N(T) = \{0\}$

$$\text{let } T(x) = T(y)$$

$$\Rightarrow T(x-y) = 0$$

$$\Rightarrow x-y \in N(T)$$

$$\Rightarrow x-y = 0$$

$$\Rightarrow x=y$$

$$\Rightarrow T \text{ is I.T.}$$

Ex above example nullity $T = 1$

$\Rightarrow T$ is not 1-1.

(nullity of $T = 0$)

Th. Let V & W be a V.S. of equal (finite) dimension, & let $T: V \rightarrow W$ be linear. Then the following are equivalent.

- (a) T is 1-1
- (b) T is onto
- (c) $\text{rank } T = \dim V$.

Pr from the dimension Theorem.

$$\text{nullity}(T) + \text{rank}(T) = \dim(V)$$

from above Th. T is 1-1 iff $N(T) = \{0\}$
 iff nullity $T = 0$ iff $\text{rank } T = \dim V$.

from above Th.

T is 1-1

$\Leftrightarrow N(T) = \{0\}$

$\Leftrightarrow \text{nullity}(T) = 0$

$\Leftrightarrow \text{rank}(T) = \dim V$

$\Leftrightarrow \text{rank}(T) = \dim W$

$\Leftrightarrow \dim(R(T)) = \dim W$.

and $\text{range } T$ is subspace of W .

$\Leftrightarrow R(T) = W$. $\Leftrightarrow T$ is onto.

If V is not finite dimensional and $T: V \rightarrow V$ is linear, then T is not onto and not equivalent. (Exercise 15, 16 & (27))

In above 2 Thms. linearity of T is essential as we can have examples from \mathbb{R} to \mathbb{R} that are not 1-1 but are onto & vice versa.

$$f: \mathbb{R} \rightarrow \mathbb{R} \\ f(x) = 2x.$$

Ex. $T: P_2(\mathbb{R}) \rightarrow P_3(\mathbb{R})$ be a linear transformation
 $\dim = 3 \quad \dim = 4$

$$T(f(x)) = 2f'(x) + \int_0^x 3f(t) dt.$$

Now:

$$\begin{aligned} R(T) &= \text{span} \{ T(1), T(x), T(x^2) \} \\ &= \text{span} \left\{ 3x, 2 + \frac{3x^2}{2}, 4x + x^3 \right\} \end{aligned}$$

Since $3x, 2 + \frac{3x^2}{2}, 4x + x^3$ is L.I. (set of poly. of diff. deg.)

$$\text{rank}(T) = 3.$$

Since $\dim P_3(\mathbb{R}) = 4$ T is not onto.

From dim Thm.

$$\text{nullity } T + 3 = 4$$

$$\Rightarrow \text{nullity } T = 1 \Rightarrow N(T) = \{0\}$$

$\Rightarrow T$ is 1-1.

~~Thm~~ If $T: V \rightarrow W$ is 1-1 then L.I. subsets of V are mapped to L.I. subsets of W .
 If T is onto L.T. then if $\text{span } S = V$ then $\text{span } T(S) = W$.

classmate
 Date _____
 Page _____
 Subject _____
 24

Ex let $T: F^2 \rightarrow F^2$ be a linear T. s.t.
 $T(a_1, a_2) = (a_1 + a_2, a_1)$. $\{ \dim F^2 = 2 \}$

clearly $N(T) = \{0\}$.

\Rightarrow ~~clearly~~ T is 1-1

$\Rightarrow T$ is onto (by above Thm).

In exercise 14. T is linear & 1-1 then a

subset S is L.I. iff $T(S)$ is L.I. ✓

Ex Let $T: P_2(\mathbb{R}) \rightarrow \mathbb{R}^3$ be a L.T.

$$T(a_0 + a_1x + a_2x^2) = (a_0, a_1, a_2)$$

clearly T is linear & 1-1.

$$\text{let } S = \{ 2 - x + 3x^2, x + x^2, 1 - 2x^2 \}$$

then S is L.I. in $P_2(\mathbb{R})$ because.

$$T(S) = \{ (2, -1, 3), (0, 1, 1), (1, 0, -2) \}$$

L.I. in \mathbb{R}^3 .

~~(Because T is 1-1 & onto $\Rightarrow T^{-1}$ is 1-1 & onto s.t. L.I. subsets of \mathbb{R}^3 are mapped to L.I. subsets of $P_2(\mathbb{R})$.)~~

Thm Let V & W be vector spaces over F and

Suppose that $\{v_1, v_2, \dots, v_n\}$ is basis for V .

For w_1, w_2, \dots, w_n in W , there exist exactly

one linear transformation $T: V \rightarrow W$ such

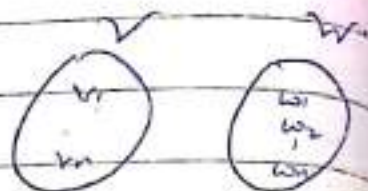
that $T(v_i) = w_i$ for $i=1, 2, \dots, n$.

Pr: Let $x \in V_n$. Then

$$x = \sum_{i=1}^n a_i v_i \quad \text{where } a_i \text{'s are unique scalars}$$

Define $T: V \rightarrow W$.

$$\text{by } T(x) = \sum_{i=1}^n a_i w_i$$



(a) T is linear.

Let $u, v \in V$ & $d \in F$

Then $u = \sum b_i v_i$ & $v = \sum c_i v_i$ for some scalars b_i & c_i

$$\Rightarrow T(u) = \sum b_i w_i \quad \& \quad T(v) = \sum c_i w_i$$

$$\Rightarrow d u + v = \sum (d b_i + c_i) v_i$$

$$\begin{aligned} T(d u + v) &= \sum (d b_i + c_i) w_i = d \sum b_i w_i + \sum c_i w_i \\ &= d T(u) + T(v) \end{aligned}$$

(b) $T(v_i) = w_i \quad \forall i = 1, \dots, n$

because

$$T(x) = T\left(\sum a_i v_i\right) = \sum a_i T(v_i) = \sum a_i w_i$$

$$\Rightarrow T(v_i) = w_i$$

(c) T is unique.

Let $u: V \rightarrow W$ be linear & $u(v_i) = w_i \quad \forall i = 1, \dots, n$

Then for $x \in V$ with $x = \sum a_i v_i$

$$u(x) = u\left(\sum a_i v_i\right) = \sum a_i u(v_i) = \sum a_i w_i = T(x)$$

$$\Rightarrow u = T$$

Cor Let v & w be v.s. and suppose that V has a finite basis $\{v_1, v_2, \dots, v_n\}$. If $U, T: V \rightarrow W$ are linear and $U(v_i) = T(v_i)$ for $i=1, 2, \dots, n$ then $U=T$.

Ex Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a l.t. s.t.
 $T(a_1, a_2) = (2a_2 - a_1, 3a_1)$
 and suppose that $U: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is linear.
 If we know that $U(1, 2) = (3, 3)$ and
 $U(1, 1) = (1, 3)$ then $U=T$ because $\{(1, 2), (1, 1)\}$
 is basis for \mathbb{R}^2 (from above cor).

Sec 2.1 Ex

2-11, -16, 17, 21, 37, 38, 20

U \exists ~~l.t.~~ l.t. $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ s.t.
 ~~$T(1, 0) = (1, 4)$ & $T(1, 1) = (2, 5)$~~
 $T(1, 1) = (1, 0, 2)$ & $T(2, 3) = (1, -1, 4)$
 what is $T(8, 11)$?

$\{ (1, 1), (2, 3) \}$ is l.i. (i.e. basis then by const thm)

Let $a(1, 1), b(2, 3) = (0, 0)$

as $a+2b=0$
 $a+3b=0$

so $\{ (1, 1), (2, 3) \}$ is l.i.

$\Rightarrow b=0$
 $\Rightarrow a=0$

\Rightarrow it is basis for \mathbb{R}^2 (dim=2)

So by last th. \exists a unique L.T.

$$T: V \rightarrow W \text{ o.d.}$$

$$T(1,1) = (1,0,2)$$

$$\& T(2,3) = (1,-1,4)$$

$$T(8,11) = ?$$

$$\text{Let } (8,11) = a(1,1) + b(2,3)$$

$$\Rightarrow a + 2b = 8$$

$$a + 3b = 11$$

$$\Rightarrow b = 11 - 8 = 3$$

$$\Rightarrow a = 8 - 2b = 8 - 6 = 2$$

$$\Rightarrow (8,11) = 2(1,1) + 3(2,3)$$

$$\Rightarrow T(8,11) = 2T(1,1) + 3T(2,3)$$

$$= 2(1,0,2) + 3(1,-1,4)$$

$$= (5, -3, 16)$$

$$T(a,b) = \alpha(a,b)$$

$$(a,b) = \alpha(1,1) + \beta(2,3)$$

$$\Rightarrow \alpha + 2\beta = a$$

$$\alpha + 3\beta = b$$

$$\Rightarrow \beta = b - a$$

$$\Rightarrow \alpha = a - 2\beta = a - 2(b - a) = 3a - 2b$$

$$\Rightarrow (a,b) = (3a - 2b)(1,1) + (b - a)(2,3)$$

$$T(a,b) = (3a - 2b)T(1,1) + (b - a)T(2,3)$$

$$= (3a - 2b)(1,0,2) + (b - a)(1,-1,4)$$

$$= (2a - b, a - b, 2a)$$

$$= (2a - b, a - b, 2a)$$

$$\Rightarrow T(8,11) = (16 - 11, 8 - 11, 16)$$

$$= (5, -3, 16)$$

12. Is there a L.T. from $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ s.t.

$$T(1,0,3) = (1,1) \text{ \& } T(-2,0,-6) = (2,1) ?$$

No because if T is linear then

$$T(-2,0,-6) = T(-2(1,0,3)) = -2T(1,0,3)$$

$$= -2(1,1)$$

$$= (-2, -2)$$

$$\neq (2,1)$$

13. $T: V \rightarrow W$ be linear.

If $\{w_1, \dots, w_k\}$ is L.I. subset of $R(T)$

& $S = \{v_1, \dots, v_k\}$ s.t. $T(v_i) = w_i$; $i=1, \dots, k$.

then S is L.I.

i.e. T-s.t. if T is L.T. then
preimage of L.I. subset is L.I.

Pr:

Pr:

$$\text{Let } a_1 v_1 + a_2 v_2 + \dots + a_k v_k = 0$$

$$\Rightarrow T(\sum a_i v_i) = 0$$

$$\Rightarrow \sum a_i T(v_i) = 0 \quad (T \text{ is L.T.})$$

$$\Rightarrow \sum a_i w_i = 0$$

but $\{w_i\}$ is L.I.

$$\Rightarrow a_i = 0 \quad \forall i$$

$$\Rightarrow \{v_i\} \text{ is L.I.}$$

14. Let V & W be V.S. & $T: V \rightarrow W$ be linear.

(a) T is 1-1 iff T carries L.I. subsets of V into L.I. subsets of W .

(b) If T is 1-1 then a subset S of V is L.I. iff $T(S)$ is L.I.

(c) Suppose $\beta = \{v_1, v_2, \dots, v_n\}$ is a basis for V and T is 1-1 & onto. prove that $T(\beta)$ is basis for W .

pr: (a) let T is H

B. S is L.I subset of V

T.S. $\forall T(S)$ is L.I in w .

conv: let if S is L.I $\Rightarrow T(S)$ is L.I.

T.S. T is 1-1

let T is not 1-1

$\Rightarrow N(T) \neq \{0\}$ (both u, v)

$\Rightarrow \exists x \in N(T)$

$n \cdot x \neq 0$

$r \cdot x \neq 0$ but

$T(x) = 0$

$\Rightarrow \exists \{x\}$ is L.I

but $\{T(x)\}$ is

not L.I.

(non zero scalar

in L.I & $\{0\}$ in L.I)

contradiction on what

T sends L.I onto

L.I.

$\Rightarrow T$ is 1-1.

let $S = \{v_1, v_2, \dots, v_n\}$.

then $T(S) = \{T(v_1), T(v_2), \dots, T(v_n)\}$.

let $\sum_{i=1}^n a_i T(v_i) = 0$.

$T(\sum a_i v_i) = 0 = T(0)$ (T is linear)

$\sum a_i v_i = 0$ (T is 1-1)

but $\{v_i\}$ is L.I.

$\Rightarrow a_i = 0 \forall i$

$\Rightarrow \{T(v_i)\}$ is L.I.

(b) let $\{T(v_i)\}$ is L.I

T.S. $\{v_i\}$ is L.I.

let $\sum a_i v_i = 0$

conv: let $\{v_i\}$ is L.I.

T.S. $\{T(v_i)\}$ is L.I

proof by (a)

$\Rightarrow T(\sum a_i v_i) = T(0) = 0$

$\Rightarrow \sum a_i T(v_i) = 0$ (T is 1-1)

but $\{T(v_i)\}$ is L.I.

$\Rightarrow a_i = 0 \forall i = 1, \dots, n$

$\Rightarrow \{v_i\}$ is L.I.

do use of 1-1 here
as it is same as a.i.3 above

(c)

β is basis of V .

$\Rightarrow \beta$ is l.i. & $\text{span } \beta = V$.

$\Rightarrow T(\beta)$ is l.i. (as T is 1-1)

T.S.T. $\text{span } T(\beta) = W$.

Let $x \in W$.

$\Rightarrow \exists v \in V$

s.t. $T(v) = x$ (as T is onto)

$\Rightarrow v = \sum a_i v_i$ for some scalars a_i

$\Rightarrow T(v) = \sum a_i T(v_i)$

$\Rightarrow x = T(v) = \sum a_i T(v_i)$

$\Rightarrow x \in \text{span } T(\beta)$

$\Rightarrow W \subseteq \text{Span } T(\beta)$

$\Rightarrow \text{Span } T(\beta) = W$.

LS: $P(R) \rightarrow$ v.s. of poly. over R .

$T: P(R) \rightarrow P(R)$ by $T(f(x)) = \int_0^x f(t) dt$.

T.S.T T is linear & 1-1 but not onto.

Clearly $T(cf+g) = \int_0^x (cf+g) = c \int_0^x f + \int_0^x g$

$$\int f = \int g \implies T(f) = T(g)$$

$$\implies T(f-g) = 0$$

$$\implies \int_0^x (f-g) = 0$$

~~$$\implies \int_0^x (f-g) = 0$$

$$\implies \int_0^x f = \int_0^x g$$

$$\implies f = g$$~~

$$\implies f-g = 0$$

$$\implies f = g$$

$$\implies T \text{ is 1-1}$$

not onto

clearly $f(x) = 1 \in P(\mathbb{R})$

but there no $f(x) \in P(\mathbb{R})$ s.t.

$$\int_0^x f(t) dt = 1.$$

So T is not onto.

(prop. of integral)

16. $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$

$$T(f(x)) = f'(x)$$

Clearly T is linear.

claw T is onto but not 1-1.

Let $a_0 + a_1x + \dots + a_nx^n \in P(\mathbb{R})$

then its preimage is

$$a_0x + \frac{a_1}{2}x^2 + \dots + \frac{a_n}{n+1}x^{n+1} \in P(\mathbb{R})$$

So T is onto.

not 1-1

Let $T(f) = T(g)$

$$\Rightarrow f' = g'$$

$$\Rightarrow f' - g' = 0$$

$$\Rightarrow (f - g)' = 0 \quad (\Rightarrow f - g = \text{const.})$$

$$\Rightarrow f - g = 0$$

$$\Rightarrow f = g + \text{const.}$$

$$\Rightarrow f \neq g$$

Let $f(x) = 2$, $g(x) = 3$

then $f' = 0$ & $g' = 0$

but $f \neq g$.

See 2.1 2-11-16, 17, 21, 37, 38, 20

(1)

2. $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ $T(a_1, a_2, a_3) = (a_1, a_2, 2a_3)$

$$N(T) = \{ (a, a, 0) \}$$

$$= \{ a(1, 1, 0) \}$$

$$\text{basis} = \{ (1, 1, 0) \}$$

$$\dim N(T) = 1 \Rightarrow \dim R(T) = 2 \quad (2+2=3=\dim V)$$

$\Rightarrow T$ is not 1-1 but onto.

3. $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$; $T(a_1, a_2) = (a_1, a_2, 0, 2a_1, -a_2)$

$$N(T) = \{ (a_1, a_2) ; a_1 + a_2 = 0, 2a_1 - a_2 = 0 \}$$

$$\Rightarrow a_1 = -a_2 \text{ \& } a_1 = \frac{a_2}{2}$$

$$\Rightarrow \frac{a_2}{2} = -a_2$$

$$\Rightarrow \frac{3}{2}a_2 = 0 \Rightarrow a_2 = 0$$

$$\Rightarrow a_1 = 0$$

$$N(T) = \{ 0 \}$$

$\Rightarrow T$ is 1-1

$$(\text{dim } N(T) + \dim R(T) = \dim V)$$

$$0 + 2 = 2$$

$$\Rightarrow \dim R(T) = 2 - 0 = 2$$

$\Rightarrow T$ is not onto.

4. $T: M_{2 \times 3} \rightarrow M_{2 \times 2}$

$$T \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{pmatrix} = \begin{pmatrix} 2a_{11} - a_{12} & a_{13} + 2a_{12} \\ 0 & 0 \end{pmatrix}$$

$$N(T) : 2a_{11} = a_{12}, a_{13} = -2a_{12} = -2(2a_{11}) = -4a_{11}$$

$$= \begin{pmatrix} a_{11} & 2a_{11} & -4a_{11} \\ a_{21} & a_{22} & a_{23} \end{pmatrix} = a_{11} \begin{pmatrix} 1 & 2 & -4 \\ 0 & 0 & 0 \end{pmatrix} + a_{21} \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} + a_{22} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} + a_{23} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\dim N(T) = 4 \Rightarrow T \text{ is not 1-1}$$

$$\dim R(T) = \dim V - \dim N(T) = 6 - 4 = 2$$

5. $T: P_2(P) \rightarrow P_3(P)$; $Tf(x) = xf(x) + f'(x)$

$\beta = \{1, x, x^2\}$,
 $\gamma = \{1, x, x^2, x^3\}$

$T1 = x \cdot 1 + 0 = 0 \cdot 0 + 1 \cdot x + 0 \cdot x^2 + 0 \cdot x^3$
 $Tx = x \cdot x + 1 = 1 \cdot 1 + 0 \cdot x + 1 \cdot x^2 + 0 \cdot x^3$
 $Tx^2 = 2x = 0 \cdot 0 + 2 \cdot x + 0 \cdot x^2 + 0 \cdot x^3$

$[T]_{\beta} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix}$

$N(T)$
 $xf(x) + f'(x) = 0$
 $\Rightarrow f'(x) = -xf(x)$
 $\Rightarrow \frac{f'(x)}{f(x)} = -x$
 $\Rightarrow \ln|f(x)| = -\frac{x^2}{2}$
 $\Rightarrow f(x) = e^{-\frac{x^2}{2}} \notin P_2(P)$

$\text{Span } T(\beta) = R(T)$

$T(\beta) = \{x, 1+x^2, 2x\}$
 $x^2 + 2x$

is L.I.

so rank $K T = 3$

$\Rightarrow N(T) = \{0\}$

$\Rightarrow \dim N(T) = 0$

$\Rightarrow \dim R(T) = 3 = \dim P_2(P)$

$\Rightarrow T$ is 1-1 but not onto.

6. $T: M_{nn} \rightarrow F$

$T(A) = \text{tr}(A)$

$\text{tr}(A) = 0$

$\Rightarrow \sum_{i=1}^n a_{ii} = 0$

$\Rightarrow a_{nn} = -\sum_{i=1}^{n-1} a_{ii}$

$A = \begin{pmatrix} a_{11} & & \\ & a_{22} & \\ & & \dots & -a_{11} - a_{22} - \dots - a_{n-1, n-1} \end{pmatrix}$

\Rightarrow basis = $E^{11} - E^{nn}, E^{22} - E^{nn}, \dots, E^{(n-1)(n-1)} - E^{nn}, E^{12}, \dots, E^{1n}, E^{21}, E^{22}, \dots$

$\dim N(T) = n^2 - 1$

$\Rightarrow \dim R(T) = n^2 - (n^2 - 1) = 1 = \dim F$

$\Rightarrow T$ is not 1-1 but onto

7

2.1

2

10. $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$T(1,0) = (1,4)$ & $T(1,1) = (2,5)$

$(x,y) = a(1,0) + b(1,1)$

$\Rightarrow a + b = x$

$b = y$

$\Rightarrow a = x - y$

$\Rightarrow (x,y) = (x-y)(1,0) + y(1,1)$

~~$\Rightarrow T(x,y) = (x-y)T(1,0) + yT(1,1)$~~

$\Rightarrow T(x,y) = (x-y)T(1,0) + yT(1,1)$

$= (x-y)(1,4) + y(2,5)$

$= (x-y+2y, 4x-4y+5y)$

$= (x+y, 4x+y)$

$\Rightarrow T(2,3) = (5, 4 \cdot 2 + 3) = (5, 11)$

25 T is 1-1

Let $T(x,y) = T(a,b)$

$\Rightarrow (x+y, 4x+y) = (a+b, 4a+b)$ or $N(T) = \{(a,b) \mid T(a,b) = (0,0)\}$

$\Rightarrow x+y = a+b$

$4x+y = 4a+b$

$\Rightarrow 3x + (a+b) = 4a+b$

$\Rightarrow 3x = 3a$

$\Rightarrow x = a$

$\Rightarrow y = b$

$\Rightarrow (x,y) = (a,b)$

$\Rightarrow T$ is 1-1

$= \{(x,y) \mid (x+y, 4x+y) = (0,0)\}$

$= \{(x,y) \mid x+y=0, 4x+y=0\}$

$= \{(0,0)\}$

11-16 in copy.

2.1 17 $T: V \rightarrow W$ $\dim V = n, \dim W = m$

(a) if $n < m$, T cannot be onto
 $\dim R(T) + \dim N(T) = \dim V = n$

$$\Rightarrow \dim R(T) = n - \dim N(T) \leq n < m = \dim W$$

$\Rightarrow R(T) \neq W$

$\Rightarrow T$ cannot be onto

(b) if $n > m$ T cannot be 1-1

$$\dim N(T) = \dim V - \dim R(T)$$

$$= n - \dim R(T)$$

$$\geq n - \dim W = n - m$$

~~is non-zero.~~

$$\left(\begin{array}{l} \dim(R(T)) \leq \dim W \\ -\dim R(T) \geq -\dim W \end{array} \right)$$

$$\Rightarrow \dim N(T) \geq n - m > 0$$

$$\Rightarrow \dim N(T) \neq 0$$

$$\Rightarrow N(T) \neq \{0\}$$

$\Rightarrow T$ can't be 1-1.

2.2 $T: V \rightarrow W$ is linear

$V_1 \subseteq V$ & $W_1 \subseteq W$ are subsp. of V & W resp

T.S.T $T(V_1)$ is subsp. of W and $T^{-1}(W_1) = \{x \in V; T(x) \in W_1\}$ is subsp. of V .

clearly $T(V_1) = \{T(x); x \in V_1\}$ is a subset of W

let $x_1, x_2 \in T(V_1)$

$$\Rightarrow x_1 = T(v_1), x_2 = T(v_2) \text{ for some } v_1, v_2 \in V_1$$

$$\Rightarrow x_1 + x_2 = T(v_1) + T(v_2) = T(v_1 + v_2) \in T(V_1) \text{ as } V_1 \text{ is a subsp.}$$

$$\cdot ax_1 = aT(v_1) = T(av_1) \in T(V_1)$$

$\Rightarrow T(V_1)$ is subsp. of W .

clearly $T^{-1}(W_1)$ is a subset of V .

let $v_1, v_2 \in T^{-1}(W_1)$

$$\Rightarrow v_1, v_2 \in T^{-1}(W_1) \Rightarrow T(v_1) + T(v_2) \in W_1$$

$$\text{let } T(v_1) = w_1 \text{ \& } T(v_2) = w_2$$

$$\Rightarrow T(v_1 + v_2) = w_1 + w_2 \in W_1$$

$$\Rightarrow v_1 + v_2 \in T^{-1}(W_1)$$

$$\text{if } T(av_1) = aT(v_1) \in W_1$$

$$\Rightarrow av_1 \in T^{-1}(W_1)$$

$$\Rightarrow T^{-1}(W_1) \text{ is subsp. of } V$$

21 V is V.S. of sequences.

$T, U: V \rightarrow V$ s.t.

$$T(a_1, a_2, \dots) = (a_2, a_3, \dots) \quad \& \quad U(a_1, a_2, \dots) = (0, a_1, a_2, \dots)$$

↳ left shift

↳ right shift

let $x = (a_1, a_2, \dots)$ & $y = (b_1, b_2, \dots)$

① T is linear

$$\begin{aligned} T(x+y) &= T(a_1+b_1, a_2+b_2, \dots) \\ &= (a_2+b_2, a_3+b_3, \dots) \\ &= \cancel{T(x)} + T(y) \\ &= (a_2, a_3, \dots) + (b_2, b_3, \dots) \\ &= T(x) + T(y) \end{aligned}$$

∴ we can prove for U .

$$\begin{aligned} T(ax) &= (aa_1, aa_2, \dots) \\ &= a(a_1, a_2, \dots) \\ &= aT(x) \end{aligned}$$

② $\Rightarrow T$ is linear

② T is onto but not 1-1

let $x = (a_1, a_2, \dots) \in V$

$\Rightarrow \exists (1, a_1, a_2, \dots) \in V$

$$\& T(1, a_1, a_2, \dots) = (a_1, a_2, \dots)$$

$\Rightarrow T$ is onto

not 1-1

$$T(1, a_1, a_2, \dots) = T(0, a_1, a_2, \dots) = (a_1, a_2, \dots)$$

but $(1, a_1, a_2, \dots) \neq (0, a_1, a_2, \dots)$

(3) V is 1-1 but not onto.

$$\det V(a_1, a_2, \dots) = V(b_1, b_2, \dots)$$

$$\Rightarrow (0, a_1, a_2, \dots) = (0, b_1, b_2, \dots)$$

$$\Rightarrow (a_1, a_2, \dots) = (b_1, b_2, \dots)$$

$$\Rightarrow V \text{ is 1-1}$$

not onto

For $(a_1, a_2, \dots) \in V$, $a_1 \neq 0$
there is no preimage in V under T .

37 $T(kt+j) = T(k) + T(j)$

T.S.T If V is a V.S over rationals, then T is linear.

~~$T(ax) = T(a)x$~~ T.S.T $T(ax) = aT(x)$ $a \in \mathbb{Q}$.

① a is ~~real~~ positive integer

$$T(ax) = T(\underbrace{x + \dots + x}_a)$$

$$= T(x) + T(x) + \dots + T(x)$$

$$= aT(x)$$

② a is -ive integer.

$$T(0ax) = T((-a)(-x))$$

$$= T(\underbrace{(-x) + (-x) + \dots + (-x)}_{-a})$$

$$= T(-x) + T(-x) + \dots + T(-x)$$

$$= (-a)T(-x)$$

Now $T(x + (-x)) = T(0) = 0$

$$\Rightarrow T(x) + T(-x) = 0$$

$$\Rightarrow T(-x) = -T(x)$$

$$= (-a)(-1)T(x) = aT(x)$$

a is rational no. say $a = \frac{\delta}{\zeta}$

$$\begin{aligned}
 T(ax) &= T\left(\frac{\delta}{\zeta}x\right) = T(\delta y) \quad y = \frac{1}{\zeta}x \in V \\
 &= \delta T(y) \\
 &= \delta T\left(\frac{x}{\zeta}\right)
 \end{aligned}$$

$$\begin{aligned}
 \text{Now } T(x) &= T\left(\zeta \cdot \frac{x}{\zeta}\right) \\
 &= \zeta T\left(\frac{x}{\zeta}\right)
 \end{aligned}$$

$$\Rightarrow T\left(\frac{x}{\zeta}\right) = \frac{1}{\zeta} T(x)$$

$$\Rightarrow T(ax) = \delta T\left(\frac{x}{\zeta}\right) = \frac{\delta}{\zeta} T(x) = a T(x)$$

38

$$T: \mathbb{C} \rightarrow \mathbb{C}, T(z) = \bar{z}$$

T.S.T. T is additive i.e. $T(x+y) = Tx + Ty$
 but T is not linear.

$$\begin{aligned}
 T(z_1 + z_2) &= T(a+ib + c+id) \\
 &= T(a+c + i(b+d)) \\
 &= a+c - i(b+d) \\
 &= a-cb + c-id \\
 &= T(a+ib) + T(c+id)
 \end{aligned}$$

$$\begin{aligned}
 \text{but } T(iz) &= T(i(a+ib)) = T(-b+ia) \\
 &= -b-ia = -(b+ia) \\
 &= -i(a+ib) = \bar{i} \bar{z}
 \end{aligned}$$

$$b. i Tz = i \bar{z} = i(a-ib)$$